

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	72	@ad<"20031110" and (simulat\$3 with control with system) and animat\$3 and calibrat\$3 and (measur\$3 or measurement) and model\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:43
S2	2	10/290538	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:30
S4	147	judd with robert	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:31
S5	1	"6823280".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:31
S6	77	@ad<"20031110" and (simulat\$3 with (robot or machine or tool)) and animat\$3 and calibrat\$3 and (measur\$3 or measurement) and model\$3 and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:44
S7	47	@ad<"20031110" and (simulat\$3 with (robot or machine)) and animat\$3 and calibrat\$3 and (measur\$3 or measurement) and model\$3 and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:48
S9	103	S8 and (dynamical\$2 with reconfigurable with module)	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:55
S10	97	S9 and interface	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:50
S11	203481	@ad<"20031110" and (simulat\$3 with (robot or machine)) and animat\$3 and server and target communication and module and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:02

EAST Search History

S12	103	S11 and (dynamical\$2 with reconfigurable with module)	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:55
S13	203448	@ad<"20031110" and (simulat\$3 with robot) and animat\$3 and server and target communication and module and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:57
S14	103	S13 and (dynamical\$2 with reconfigurable with module)	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:03
S15	1157	@ad<"20031110" and (simulat\$3 with robot)	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:01
S16	203448	S15 and animat\$3 and server and target communication and module and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:58
S17	155	S15 and animat\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:58
S18	203448	S17 and server and target communication and module and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:58
S19	203448	S17 and server and target communication and module and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:58
S20	203448	S17 and server and target communication and module and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:59
S21	118	S17 and model\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:03

EAST Search History

S22	63	S21 and module	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 13:59
S23	363	@ad<"20031110" and (simulat\$3 and (control with system) and animat\$3 and ("700"/\$ or "702"/\$))	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:02
S24	164	S23 and communication and module and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:02
S25	148	S24 and model\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:09
S26	0	S25 and (dynamical\$2 with reconfigurable with module)	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:04
S27	0	S25 and (reconfigurable with module)	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:04
S28	27	S25 and (reconfigurable)	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:04
S30	27	S28 and dynamic\$5	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:05
S31	121	S25 not S30	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:10
S32	39	S31 and robot	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:10

EAST Search History

S33	81	@ad<"20031110" and (simulat\$3 with (robot or machine)) and animat\$3 and server and target and communication and module and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:16
S34	1	10/290536	US-PGPUB; USPAT; USOCR; EPO; JPO; IBM_TDB	OR	ON	2007/08/28 16:30


[Web](#) [Images](#) [Video](#) [News](#) [Maps](#) [more »](#)

simulation control system dynamic reconfigura

- 2003

[Ad](#)
[Sc](#)
[Sc](#)
Scholar All articles - **Recent articles** Results 21 - 30 of about 4,660 for simulation control system c

All Results
[D Goldberg](#)
[A Law](#)
[W Kelton](#)
[J Holland](#)
[J Peterson](#)

A case study in tool-aided analysis of discretely controlled continuous systems: the two tanks ... - all 5 versions »

S Kowalewski, O Stursberg, M Fritz, H Graf, I ... - Hybrid Systems V, 1999 - Springer
 ... for a sound verification of the **control** program ... evolution is given by a DAE-System
 (the 'flow ... 7. Visualization of the **simulation** results by gRMS (parameter set ...

Cited by 40 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

Distributed control for a modular, reconfigurable cliff robot - all 3 versions »

P Pirjanian, C Leger, E Mumm, B Kennedy, M Garrett ... - Robotics and Automation, 2002.
 Proceedings. ICRA'02. IEEE ..., 2002 - [ieeexplore.ieee.org](#)

... based tether controller using the **simulator**, and performed ... Sensor Fusion and
 Decentralized **Control** Nov ... reconfiguring robots." IEEE Intelligent **Systems** 134 (July ...

Cited by 16 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

Emergent structures in modular self-reconfigurable robots - all 5 versions »

H Bojinov, A Casal, T Hogg - Robotics and Automation, 2000. Proceedings. ICRA'00. IEEE
 ..., 2000 - [ieeexplore.ieee.org](#)

... In most current modular **robot systems** the modules remain attached ... A **simulation** of
 the Proteo **robot** platform was used to run a number of **control** experiments ...

Cited by 74 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

A rapidly deployable manipulator system - all 18 versions »

CJJ Paredis, HB Brown, PK Khosla - Robotics and Automation, 1996. Proceedings., 1996
 IEEE ..., 1996 - [ieeexplore.ieee.org](#)

... on the same RTPUs used to **control** the actual ... Figure 7 shows an RMMS **simulation**
 compared

with the ... a **Reconfigurable** Modular Manip- ulator **System** which currently ...

Cited by 43 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

DLR-Hand II: next generation of a dextrous robot hand - all 2 versions »

J Butterfass, M Grebenstein, H Liu, G Hirzinger - Robotics and Automation, 2001.
 Proceedings 2001 ICRA. IEEE ..., 2001 - [ieeexplore.ieee.org](#)

... Figure 4. **Simulation** of Hand II in power-grasp ... Hogan [2] introduced the impedance
control scheme, which will improve **system dynamic** characteristics greatly ...

Cited by 107 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

Development of a reconfigurable flight control law for tailless aircraft - all 6 versions »

AJ Calise, S Lee, M Sharma - Journal of Guidance, **Control**, and Dynamics, 2001 -
[pdf.aiaa.org](#)

... 12 Piloted **simulation** and ight-test results for the X-36 ... NN-Based Adaptive **Control**
 Architecture Feedback Inversion Consider a nonlinear **system** in the ...

Cited by 83 - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

On device abstractions for portable, reusable robot code - all 17 versions »

RT Vaughan, BP Gerkey, A Howard - Intelligent Robots and Systems, 2003.(IROS 2003). ...,
 2003 - [ieeexplore.ieee.org](#)

... to allow code to run unchanged in **simulation** and on ... Thus we have extended to **robot control** the device model that is used in most operating **systems**, where, for ...

[Cited by 84](#) - [Related Articles](#) - [Web Search](#)

Advances in network simulation - all 32 versions »

LE Breslau, D Fall, K Floyd, S Heidemann, J Helmy, ... - Computer, 2000 -
ieeexplore.ieee.org

... simple and pure operations are free of built-in **control** policies and ... **Ns simulator**
(emulation mode ... Packet capture and generation interface Local operating **system** ...

[Cited by 420](#) - [Related Articles](#) - [Web Search](#) - [BL Direct](#)

Process control system with reconfigurable expert rules and control modules - all 4 versions »

RD Skeirik - US Patent 5,006,992, 1991 - Google Patents

... "An Academic/Industry Project to Develop and Ex -pert **System** for Chemical Process ...

"Process **Control** Using Modular ... "On-Line Process **Simulation** Techniques in ...

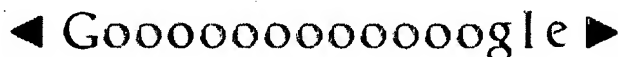
[Cited by 68](#) - [Related Articles](#) - [Web Search](#)

[book] Petri Net Theory and the Modeling of Systems - all 2 versions »

JL Peterson - 1981 - Prentice Hall PTR Upper Saddle River, NJ, USA

... Proceedings of the 24th conference on Winter **simulation**, p.955 ... de Kleer, Model-based
computing for design and **control** of **reconfigurable systems**, AI Magazine ...

[Cited by 2366](#) - [Related Articles](#) - [Web Search](#) - [Library Search](#)



Result Page: [Previous](#) [1](#) [2](#) [3](#) [4](#) [5](#) [6](#) [7](#) [8](#) [9](#) [10](#) [11](#) [12](#) [Next](#)

simulation control system dynamic reconfigurable robot OR machine OR tool

[Google Home](#) - [About Google](#) - [About Google Scholar](#)

©2007 Google